		STUDY MODULE D	ESCRIPTION FORM			
Name of the module/subject Automation			Code 1010604341010622392			
Field of study			Profile of study (general academic, practical)			
Transport Elective path/specialty			(brak) Subject offered in: Polish	2 / 4 Course (compulsory, elective) obligatory		
Cycle of	study:	-	Form of study (full-time,part-time)			
	First-cyc	cle studies	part-time			
No. of h			No. of credits			
Lectur		s: 9 Laboratory: -	Project/seminars:	- 4		
Status o	f the course in the study	program (Basic, major, other)	(university-wide, from another	field)		
		(brak)		(brak)		
Educatio	on areas and fields of sci	ence and art		ECTS distribution (number and %)		
Resp	onsible for subj	ect / lecturer:	Responsible for subje	ct / lecturer:		
EngD Wojciech Sawczuk email: wojciech.sawczuk@put.poznan.pl tel. 61 224 4510 Faculty of Transport Engineering			M.Eng Julian Kominowski email: julian.kominowski@put.poznan.pl tel. 61 665 2841 Faculty of Transport Engineering			
	rowo 3 Street, 60-965		Piotrowo 3 Street, 60-965			
Prere	quisites in term	s of knowledge, skills and	a social competencies:			
1	Knowledge	The student has a basic knowledge of automation, information technology and telecommunications, knows the basics of the theory of probabilistic processes, harmonic signals and graph theory.				
2	Skills	Student is able to apply his know	owledge in learning about and solving automation problems.			
3	Social competencies	The student is able to determine he can effectively collaborate in				
Assu	mptions and obj	ectives of the course:				
	tanding the role of au ement and vehicle mo	tomation in transport and mechan onitoring.	ics as well as improving efficien	ncy and effectiveness in traffic		
		mes and reference to the	educational results for	a field of study		
	/ledge:					
		retically founded general knowledgected issues of this discipline in tra				
	basic knowledge abou ses taking place in the	ut the life cycle of transport means em - [T1A_W06]	, both hardware and software,	and in particular about the key		
	vs the basic technique ering nature - [T1A_V	es, methods and tools used in the V07]	process of solving tasks in the	field of transport, mainly of		
Skills	:					
approp		on from various sources, including n, make their interpretation and crit 1A_U01]				
		form experiments, including mease onclusions from them - [T1A_U03		tions, interpret the obtained		
	by formulating and so ion or experimental m	olving tasks in the field of transport nethods - [T1A_U04]	t, apply properly selected meth	ods, including analytical,		
Socia	I competencies:					
		chnology knowledge and skills qui				
reason		e of knowledge in solving engineer ansport systems that led to seriou				

Assessment methods of study ou				
Final test				
Course description				
1. Definition of control, control device and automatic control,				
Definition of the set point, current value and control force,				
3. Definition of the controller, setting variable and control variable,				
Diagram and description of the open and closed control system,				
5. The system of regulation in a steady state and undetermined state and what c	5. The system of regulation in a steady state and undetermined state and what conclusions result from it,			
6. Types, characteristics of input signals and their equations,				
7. Transmission and spectral transmittance, formulas and example,				
The essence of Laplace's transformation, an example of any two transformation	ons,			
9. Kinds of elements appearing in the automatic control system with the diagram	,			
10. Connecting elements (serial, parallel, with feedback) patterns and examples,				
11. Types of linear elements, functions f (t), transmittances, characteristics, and e	examples,			
12. Frequency characteristics of Nyquist and Bego, examples on any elements,				
13. Study of static and dynamic properties (static and dynamic characteristics),				
14. Time constant and period, methods of determination on the example of any member,				
15. Tasks of regulators in the automatic control system,				
16. Distribution of regulators with description and examples,				
17. Characteristics of P, I, PI, PD and PID regulators,				
8. Error and dead zone of selected regulators,				
9. Time of integration and differentiation time on the example of selected regula	tors,			
20. Time courses on the output for ideal and real controllers.				
Basic bibliography:				
1. Żelazny M., Podstawy automatyki, Materiały pomocnicze do wykładu				
2. Rumatowski K., Podstawy automatyki cz.1, Wydawnictwo Politechniki Poznań	skiej 2004			
Rumatowski K., Podstawy automatyki cz.2, Wydawnictwo Politechniki Poznań	•			
 Urbaniak A., Podstawy automatyki, Wydawnictwo Politechniki Poznańskiej 200)1			
Additional bibliography:				
1. Horla D., Podstawy automatyki, Wydawnictwo Politechniki Poznańskiej 2003				
2. Wiak S., Mechatronika cz.2, Wydawnictwo Politechniki Łódzkiej 2010				
Result of average student's wor	kload			
Activity		Time (working hours)		
1. Preparation for the lecture		10		
2. Participation in the lecture		30		
3. Strengthening the content of the lecture		10		
4. Consultations for the lecture		2		
5. Preparation for the exam		8		
6. Participation in the exam		2		
7. Preparation for exercises		5		
3. Participation in exercises	15			
9. Strengthening the content of exercises	5			
10. Consultations for exercises	2			
11. Preparation for passing	4			
12. Participation in the credit		2		
Student's workload				
Source of workload	hours	ECTS		

Source of workload	hours	ECTS	
Total workload	100	4	
Contact hours	53	2	

Practical activities	0	0